PRODUCT DATA

4-ch. Input/HS-Tacho + 8-ch. Aux. Module LAN-XI 51.2 kHz Type 3056-A-040

Auxiliary Input Module Type 3056-A-040 is aimed at applications where you need to monitor low-frequency voltage signals along with the sound and vibration signals.

The module offers a combination of four 51.2 kHz input channels with eight simultaneously sampled low-frequency auxiliary channels.

Unique to Type 3056 is the support of high-speed tacho signals on channels 1 - 4, which allows you to record signals needed to perform angle domain analysis.

The interchangeable front panels give the flexibility to use the module with a wide range of transducers. The module works equally well both as a single-module system or as part of a large LAN-XI measurement system, making it one of the most flexible data acquisition modules available on the market.



Uses and Features

Uses

- · General sound and vibration measurements
- Angle domain analysis
- QC testing
- Record and monitor low-frequency auxiliary data along with sound and vibration data
- Engine test cells
- Data acquisition front-end module for PULSE measurement and analysis software
- Front-end for PC-based PULSE Data Recorder Type 7708
- Single-module measurements
- Multi-module measurement/distributed system
- Stand-alone recording (no PC) using LAN-XI Notar

Features

- · Four input channels with high-speed tacho signal support
- DC to 51.2 kHz input frequency range
- 131 ksamples/s sampling rate
- · Eight auxiliary input channels

- Four programmable DC output channels
- All input channels have Dyn-X technology
- Req-X technology
- Supports IEEE 1451.4 capable transducers with TEDS
- Interchangeable front panels
- Provides module status information on self-test and error conditions
- Input voltage up to 10 V_{peak} and extended range to 31.6 V_{peak}
- Absolute maximum input 60 V_{peak} without damage
- Automatic DC offset compensation
- · Extremely low noise floor
- · Selectable floating or grounded outputs
- Low out-of-band spurious noise
- Overload indicator indicates overload, incorrect conditioning and cable breaks on connected transducers
- Overload detection including out-of-band frequencies
- Full phase match among all inputs in a system, including IDA^e hardware



These multipurpose, Dyn-X input channels can be used in combination with the module's interchangeable front panels to connect and condition all relevant sound and vibration transducers including:

- Microphone preamplifier with 0 or 200 V microphone polarization voltage
- DeltaTron microphones
- Proximity probes
- Accelerometers
- DeltaTron accelerometers
- DC accelerometers (diff. input)
- Charge transducers (via DeltaTron converter)
- AC/DC
- Tachometers (power supply not available)
- · High-speed tacho signals from angle encoders

Independent Channels

The input channels on a module can be set up independently. You can set up the high-pass filters and input gain separately and attach different types of transducer to different channels.

When used with externally polarized microphones, the polarization voltage can be switched on for individual channels.

IEEE 1451.4 Transducers

All input modules support TEDS transducers. This allows automatic front-end and analyzer setup based on TEDS information stored in the transducer, for example, sensitivity, serial number, manufacturer and calibration date. The individual frequency response of a transducer can be corrected for using PULSE's Transducer Response Equalisation, REq-X, to achieve higher accuracy over extended frequency ranges.

Overload

Constant Current Line Drive (CCLD) conditioning monitors the supply voltage used by CCLD-compatible transducers. Available CCLD transducers include:

- Accelerometers
- · Charge amplifiers
- Microphone preamplifiers
- Tacho probes

If conditioning errors, such as a broken cable, are detected, an error is indicated as an overload on the specific channel connector (using a ring-LED around the connector) and in the PC software.

Overload indications for input channels include (see Specifications for details):

- Signal overload with adjustable detection level
- CCLD overload: detection of cable break, short-circuit or CCLD transducer working point fault
- Microphone preamplifier overload: detection of microphone preamplifier current consumption too high or too low
- · Common mode voltage overload relevant when input coupling is floating

Ground-loop Noise Suppression

The module's floating/grounded, differential input design and the fact that all external connections (LAN, power supply) are galvanically isolated in the module provide optimal ground-loop noise suppression.

Protection

If the signal input level to a module significantly exceeds the measuring range, the input will go into protection mode for at least 0.5 s until the signal falls again. While protected, the input is partly switched off and the input impedance is greatly increased. (The measured value will be strongly attenuated but still detectable.)

High-speed Tacho

Of the four input channels on Type 3056, channels 1 and 3 can be independently configured to support highspeed tacho signals needed to perform high-precision angle domain analysis on fast-rotating machinery and combustion engines. Channels 2 and 4 can be independently configured for tacho reference signals. The high-speed tacho signals are typically supplied from angle encoders. Note that PULSE Time Data Recorder Type 7708 supports only two high-speed tacho channels (one tacho channel and one tacho [angle] reference channel). For full support of four high-speed tacho channels, use PULSE LabShop.

	PULSE LabShop	PULSE Time Data Recorder Type 7708
Ch. 1	High-speed tacho signal or normal input	High-speed tacho signal or normal input
Ch. 2	High-speed tacho ref or normal input	High-speed tacho ref or normal input
Ch. 3	High-speed tacho signal or normal input	Normal input
Ch. 4	High-speed tacho ref or normal input	Normal input

PULSE Reflex Angle Domain Analysis Type 8740 (BP 2433) uses angle profile and key phasor information from high-speed tachometer and tachometer reference signals for angle calculation and subsequent cycle extraction for applications such as crank angle analysis.



Auxiliary Channels

Fig. 1

Angle profile (high-

used for cycle

The auxiliary channels can be used for measurement of auxiliary, pseudo-DC parameters with up to eight low-frequency (16 Hz sample rate) input channels that can be recorded along with the dynamic channels and used as logging or multi-buffer tags. Auxiliary channel settings and data are accessed via OLE2 automation interface.

Typical applications include:

- ٠ Automotive – intake pressure, thermocouples, throttle position, vehicle acceleration/braking,
- Industrial - process parameters (temperature, pressure, control position, etc.)
- ٠ Production Line Testing - PLC control parameters, environmental conditions (temperature, barometric pressure)
- Pass-by Testing environmental parameters ٠
- Auxiliary data like temperature and wind speed available as time data or as z-axis tags
- ٠ Integration of auxiliary parameters with dynamic data such as FFT, Order and CPB spectra





2233

Fig. 3 Break-out Box ZH-0699



The four programmable DC outputs are opendrain outputs that are able to sink 100 mA from an external supply of up to 24 V, sufficient for a relay. DC output without an external supply is 5 V, max. 50 mA.

Break-out Box ZH-0699, with 2×10 -pin LEMO^{*} (M) connectors, is available as an accessory and provides BNC connectors for the eight auxiliary signals and four DC outputs.

130369

Fig. 4 Auxiliary cable AO-0738-D-010



Auxiliary cable AO-0738-D-010, 2×10 -pin LEMO^{*} (M) to $8 \times BNC$ (F) plus ground, is available as an accessory (inputs only). DC outputs require a custom cable or Break-out Box ZH-0699.

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^{*} LEMO FGG.1B.310.CLAZ31.

Compliance with Standards

CE 💩 I I I I I I I I I I I I I I I I I I I	CE-mark indicates compliance with: EMC Directive and Low Voltage Directive RCM mark indicates compliance with applicable ACMA technical standards – that is, for telecommunications, radiocommunications, EMC and EME China RoHS mark indicates compliance with administrative measures on the control of pollution caused by electronic information products according to the Ministry of Information Industries of the People's Republic of China WEEE mark indicates compliance with the EU WEEE Directive
Safety	EN/IEC 61010-1 and ANSI/UL 61010-1: Safety requirements for electrical equipment for measurement, control and laboratory use
EMC Emission	EN/IEC 61000–6–3: Generic emission standard for residential, commercial, and light-industrial environments CISPR 22: Radio disturbance characteristics of information technology equipment. Class B Limits
EMC Immunity	EN/IEC 61000–6–1: Generic standards – Immunity for residential, commercial and light industrial environments EN/IEC 61000–6–2: Generic standards – Immunity for industrial environments EN/IEC 61326: Electrical equipment for measurement, control and laboratory use – EMC requirements Note: The above is only guaranteed using accessories listed in this Product Data
Temperature	IEC 60068-2-1 & IEC 60068-2-2: Environmental Testing. Cold and Dry Heat Ambient Operating Temperature: -10 to +55°C (14 to 131°F) Storage Temperature: -25 to +70°C (-13 to +158°F)
Humidity	IEC 60068–2–78: Damp Heat: 93% RH (non-condensing at 40°C (104°F))
Mechanical (Non-operating)	IEC 60068–2–6: Vibration: 0.3 mm, 2 g, 10 – 500 Hz IEC 60068–2–27: Shock: 100 g IEC 60068–2–29: Bump: 1000 bumps at: 40 g
Enclosure	IEC 60529: Protection provided by enclosures: IP 31

EFFECT OF RADIATED AND CONDUCTED RF, MAGNETIC FIELD AND VIBRATION Radiated RF: 80–2700 MHz, 80% AM 1 kHz, 10 V/m Input measured with terminated input. All values are RMS. Conducted RF immunity on all channels is only guaranteed using an external connection from measuring ground to chassis terminal

Radiated RF: 80–2700 MHz, 80% AM 1 kHz, 10	V/m
Conducted RF: 0.15-80 MHz, 80% AM 1 kHz, 1	0 V
Magnetic Field: 80 A/m, 50 Hz	
Vibration: 5–500 Hz, 12.7 mm, 15 m/s ²	

Input	Radiated RF	Conducted RF	Magnetic Field	Vibration
Direct/CCLD	<250 μV	<300 μV	<4 µV	<80 µV
Preamplifier	<250 μV	<50 μV	<8 µV	<80 μV

Specifications – LAN Interface

CONNECTOR

RJ 45 (10baseT/100baseTX) connector complying with IEEE-802.3 100baseX

Types 3660-C and -D permit the use of a ruggedized RJ45 data connector (Neutrik NE8MC-1) to screw the cable to the frame Types 3660-C and -D communicate at 1000 Mbits/s – shielded cables of type "CAT 5e" or better should be used

Individual modules communicate at 100 Mbits/s

All LAN connectors support MDIX, which means that cables may be "crossed" or not

For stand-alone modules, PoE is also supported (IEEE 802.3af). PoE requires screened shielded twisted pair (S/STP or S/FTP) CAT6 LAN cables

PROTOCOL

The following standard protocols are used:

- TCP
- DHCP (incl. Auto-IP)
- DNS (on top of UDP)
- IEEE 1588-2002 (on top of UDP)
- IP
- Ethernet

ACQUISITION PERFORMANCE

Each LAN-XI module generates data at almost 20 Mbit/s when measuring six channels at 51.2 kHz bandwidth. The modules are capable

of handling their own maximum traffic while the built-in switch in the frame's backplane has more than sufficient capacity. This means that bottlenecks can only occur outside these, for example in:

- External switches
- PC

For convenience, it is possible to daisy-chain LAN-XI frames. However, it is not recommended to daisy-chain more than two frames. For larger configurations, a star configuration with a central switch is recommended. This must have a switch capacity well beyond $N \times 20$ Mbit/s, where N is the total number of modules

PTP PERFORMANCE

PTP Synchronisation (with 1 Gigabit LAN Switch):

Typical sample synchronisation better that 200 ns (approx. $\pm 0.07^{\circ}$ @ 1 kHz, $\pm 2^{\circ}$ @ 25.6 kHz) Tested with:

- Cisco[®] SG300-10MP, 10-port 10/100/1000 Managed Gigabit Switch with Maximum PoE (8 ports)
- Netgear[®] 5-port Gigabit Switch GS105
- Better performance can be expected with a dedicated PTP switch:
- UL-0265: 10-port Gigabit Managed Switch with PTPv2 and PoE (8 ports).
- This is a dedicated PTP switch, preconfigured for optimal use with $\ensuremath{\mathsf{LAN-XI}}$

HIGH-SPEED TACHOMETER CHANNELS

Available on channels 1 to 4:

	PULSE LabShop	PULSE Time Data Recorder Type 7708
Ch. 1	High-speed tacho signal or normal input	High-speed tacho signal or normal input
Ch. 2	High-speed tacho ref or normal input	High-speed tacho ref or normal input
Ch. 3	High-speed tacho signal or normal input	Normal input
Ch. 4	High-speed tacho ref or normal input	Normal input

Analog Bandwidth: > 1 MHz @ 5 V_{peak} (TTL level) Tacho Resolution: 15 ns Max. Tacho Input Voltage: 10 V_{peak} Absolute Max. Input Voltage: $\pm 60 V_{peak}$ Trigger Level: 0.2 V to 7 V Default Trigger Level: 1.5 V Triggering on rising or falling edge

Upper RPM Limit	Max. Pulses/Revolution	Angular Resolution (°)
1000	60000	0.0000025
6000	10000	0.000015
20000	3000	0.00005
150000	400	0.00375

AUXILIARY INPUT CHANNELS (simultaneously sampled) Number of Channels: 8 DC channels in 2 × 10-pole LEMO connectors Input Connector: 2 × 10-pole LEMO Sampling Rate: 16 Hz Input Connection: Single-ended Input Voltage Range: ±10 V in one range Input Protection: 50 V Input Impedance: 1 M Ω || 300pF Precision: ±0.1% of reading ±1 mV offset (after warm up time) Noise: < 3 μ V (10 mHz – 8 Hz) measured without temperature drift and

DC offset Noise-free Dynamic Range: 120 dB (typical)

Noise-free Resolution: 19 to 20 bits (typical) Temperature Coefficient: <15 μ V/°C (typical)

Distortion: 90 dB @1 Hz 10 V_{peak} (typical)

Programmable DC Output Channels: 4 open-drain outputs (2 per connector) able to sink 100 mA from an external supply of typically 24 V, which allow simple relay control (on/off, pass/fail, etc.) via OLE2 automation interface

DC Output without External Supply: 5 V, max. 50 mA DC Output Protection: 40 V

DC Out Supply: 5 V out, max. 100 mA total for module

INPUT CHANNELS

Frequency Range		DC to 51.2 kHz Lower frequency range can be set in PULSE software			
Sampling Rate		131 ksamples/s			
A/D Conversion			2 × 2	24 bit	
Data Transfer			24	bit	
Input Voltage Range			10 \ Extended ran	/ _{peak} ge: 31.6 V _{peak}	
Input Signal	Differential	S	Signal ground is "floati	ing" (1 M Ω re: chassi	s)
Coupling	Single-Ended	Sigr	nal ground is connecte	ed to chassis ("Groun	ded")
Input Impedance			Direct, Microphone	e: 1 MΩ <300 pF	
			CCLD: >100	kΩ <300 pF	
Absolute Maximum Input			±60 V _{peak} wit	thout damage	
High-pass Filters		– 0.1 dB *	-10% @ **	–3 dB @ **	Slope
* Defined as the lower frequency, f _L , for guaranteed fulfilment of	0.1 Hz –10% analog high-pass filter 0.7 Hz –0.1 dB digital high-pass filter	0.5 Hz 0.7 Hz	0.1 Hz 0.15 Hz	0.05 Hz 0.073 Hz	-20 dB/dec.
-0.1 dB accuracy in 10 V _{peak} range ** Defined as the nominal -10%/3 dB filter frequency	1 Hz –10% digital high-pass filter 7 Hz –0.1 dB digital high-pass filter	5 Hz 7 Hz	1.0 Hz 1.45 Hz	0.5 Hz 0.707 Hz	-20 dB/dec.
	22.4 Hz -0.1 dB analog high-pass filter	22.4 Hz	15.8 Hz	12.5Hz	-60 dB/dec.
	Intensity filter (analog)	115 Hz	23.00 Hz	11.5 Hz	-20 dB/dec.
Absolute Amplitude Precision,	1 kHz, 1 V _{input}	±0.05 dB, typ. ±0.01 dB			
Amplitude Linearity	0 to 80 dB below full scale	±0.05 dB, typ. ±0.01 dB			
(linearity in one range)	80 to 100 dB below full scale	±0.2 dB, typ. ±0.02 dB			
	100 to 120 dB below full scale		typ.±0).02 dB	
	120 to 140 dB below full scale	typ. ±0.02 dB			
	140 to 160 dB below full scale	typ. ±1 dB			
Overall Frequency Response re 1 kHz, from lower limit f_L to upper limit f_U f_L is defined as the lower frequency for guaranteed fulfilment of -0.1 dB accuracy in 10 V _{peak} range (see under High-pass Filters) f_u is defined as the chosen frequency span. DC ($f_L = 0$)			±0. ±0.3 dB in 3	1 dB 31.6 V range	

INPUT CHANNELS (CONTINUED)

$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Noise		Input	Guaranteed		Typical	
• Measure in , 101z to 30 bits (0 mit), 101z to 31 bits (0 mit), 101z to			Range	Lin*	1 kHz	Lin*	1 kHz
Graph termination by 50.0 million of 10 Hz is 53.2 Hz is 10 Voxes 10 Hz is 53.2 Hz 10 Hz is 12 H	* Measured lin. 10 Hz to 25.6 kHz or lin. 10 Hz to 51.2 kHz:	Signal level <316 mV_{peak} 10 Hz to 25.6 kHz 10 Hz to 51.2 kHz	10 V _{peak}	<4 μV _{rms} <13 μV _{rms}	<25 nV _{rms} /√Hz	<3 μV _{rms} <10 μV _{rms}	<19 nV _{rms} /√Hz
Signal level - 11 Vaces 10 Hz to 52 June 10 Hz to 52 June 10 Hz to 52 June 10 Hz to 51 June 10 Hz sector any model of team 10 Hz to 51 June 10 Hz sector any model of team 10 Hz to 51 June 10 Hz sector any model of team 10 Hz to 51 June 10 Hz sector any model of team 10 Hz to 51 June 10 Hz sector any model of team 10 Hz to 51 June 10 Hz sector any model of team 10 Hz sector any model 10 Hz sector any model of team 10 Hz sector any model 10 Hz	(Input terminated by 50 Ω or less)	Signal level >316 mV_{peak} 10 Hz to 25.6 kHz 10 Hz to 51.2 kHz	10 V _{peak}	<60 μV _{rms} <350 μV _{rms}	<375 nV _{rms} /√Hz	<50 μV _{rms} <250 μV _{rms}	<313 nV _{rms} /√Hz
Signal level > 10 bt to 05 2 kHz 10 bt to 05 2 kHz (hput terminated by 50 0 r/ses) Spuntour-Ref Opmanic Range re Full-scale Input (input terminated by 50 0 r/ses) Spuntour-Ref Opmanic Sampe Label scale Input (application componencies) Imput Range Typical		Signal level <1 V _{peak} 10 Hz to 25.6 kHz 10 Hz to 51.2 kHz	31.6 V _{peak}	<20 μV rms <45 μV _{rms}	<125 nV _{rms} /√Hz	<15 μV _{rms} <35 μV _{rms}	<95 nV _{rms} /√Hz
Burlow-free Dynamic Range re Full-scale Input (mput terminate by 50 Lor energies) Imput Range Typical Sourious-free Dynamic Range is defined as the mits of the imput duration amputito the tim value of the largest spurious 10 V _{pack} 160 dB OC Offset Fe Units Scale Guaranteed 140 dB DC Offset Fe Units Scale Guaranteed Typical Measured after automatic DC compensation at current temperature when dranging from Act to DC component of the high space filter -100 dB -100 dB Constant C to DC component of the high space filter and fiftering the too DC component of the high space filter of the high space filter Guaranteed Typical Constants Guaranteed to DC component of the too DC component of the high space filter of the high space filter Guaranteed to the too DC component of the high space filter -100 dB -100 dB Constants Maximum Gain Difference (within one frame) to the high space filter Guaranteed to Difference to the high space filter Typical 0.05 dB -100 dB -100 dB Constants Maximum Phase Difference to the high space filter Guaranteed to Componence filter Typical Constants Maximum Gain Difference to the high space filter 0.6 dB from hower frequency filter, to 512 kHz 0.0005 ⁺		Signal level >1V _{peak} 10 Hz to 25.6 kHz 10 Hz to 51.2 kHz	31.6 V _{peak}	<200 μV _{rms} <1200 μV _{rms}	<1250 nV _{rms} /√Hz	<150 μV _{rms} <800 μV _{rms}	<950 nV _{rms} /√Hz
(Input minimized by SL 10 relss) 100 rptsk 100 rptsk 100 rptsk (Input minimized by SL 10 relss) 100 rptsk 100 rptsk 100 rptsk (Input minimized by SL 10 relss) 100 rptsk 140 dB DC Offset re Full Scale 100 rptsk 140 dB (Input minimized by SL 10 relss) 160 rptsk 140 dB DC Offset re Full Scale 100 rptsk 140 dB (Input minimized by SL 10 relss) 00 rptsk 140 dB (Input minimized by SL 10 relss) 00 rptsk -100 dB (Input minimized by SL 10 relss) 00 rptsk -100 dB (Input minimized by SL 10 relss) -100 rptsk -100 dB (Input minimized by SL 10 relss) -100 rptsk -100 rptsk (Input minimized by SL 10 relss) -100 rptsk -100 rptsk (Input minimized by SL 10 rsl) 0 rptsk -100 rptsk -100 rptsk (Input minimized by SL 10 rsl) 0 rptsk -100 rptsk -100 rptsk (Input minimized by SL 10 rsl) Maximum Gin Difference 0 rptsk Tptsk -100 rptsk (Input minimized by SL 10 rsl) Max	Spurious-free Dynamic Range r	e Full-scale Input	Input Range	Typical			
Spectral component (non-harmonic) 31.6 V _{peak} 140.0B OC Offest or Full Scale Survey Guaranteed Typical Messaved after automatic DC componsation at current temperature when changing fram Act DB Cocupies Guaranteed Typical Harmonic Distortion (all harmonics) -00.0B -100.0B -100.0B -100.0B Crosstalk: Between any two channels of a module or between any two channels in different modules Guaranteed Typical -100.0B -140.0B Channel-to-Channel Match Guaranteed Typical -100.0B -140.0B -100.0B -140.0B Maximum Phase Difference (within one frame) f ₁ is defined as the -0.10B frequency of the high-pass filter 0 to 51.2 kHz -100.0B 120.05 dB 2.085 dB Additional PTP sync. arror (shase difference) between modules/frames (using a single standard gigable swith) Typical standard single standard gigable swith) Typical standard gigable swith) 0 dB dF frequency imit, f ₁ , to 51.2 kHz 51.2 kHz Channel-to-Channel Match (014 y _{peak} input range) Maximum Gan Difference (within one frame) 0 dB frem lower frequency imit, f ₁ , to 51.2 kHz 120.051.2 kHz 51.2 kHz 52.6 kHz) Channel-to-Channel Match (014 yrusing intensity Phase Match	Spurious-free Dynamic Range is of full-scale amplitude to the rms val	s) Jefined as the ratio of the rms ue of the largest spurious	10 V _{peak}	160 dB			
OC Offset re Full Scale Guaranteed Typical Guaranteed Typical Harmonics) -00 dB -100 dB	spectral component (non-harmoni	c)	31.6 V _{peak}	140 dB			
Index dual metabolines, Do Completization at Lot of the emperature when DC coupled -00 dB -100 dB 100 dB Harmonic Distortion (all harmonics) -80 dB -80 dB (-80 dB B 1 HHz in 31.6 V range) Crosstalik: Between any two channels of a module or between any two channels in different modules 0 to 51.2 Hz -100 dB C 1 HHz in 31.6 V range) Crosstalik: Between any two channels of a module or between any two channels in different modules 0 to 51.2 Hz -100 dB -140 dB Channel-to-Channel Match Guaranteed Typical -140 dB -140 dB -140 dB Maximum Phase Difference (within one frame) 0.2 dB from lower frequency init, 1, 1, 12, 12, 12, 12, 12, 12, 12, 12,	DC Offset re Full Scale	poportion of ourront tomporature	when	Guara	anteed	Тур	oical
Harmonic Distortion (all harmonics) Guaranteed Typical Creastalk: Between any two channels of a module or between any two channels alferent modules Frequency Range Guaranteed Typical Creastalk: Between any two channels of a module or between any two channels alferent modules Maximum Gain Difference fr, is defined as the -0.1 dB frequency of the high-pass filter 0 to 51.2 kHz -100 dB -140 dB Channel-to-Channel Match (10 V _{pask} input range) Maximum Gain Difference fr, is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency limit, fr, to 51.2 kHz ±0.05 dB Maximum Phase Difference (within one frame) fr, is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency limit, fr, to 51.2 kHz ±0.05 dB Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigabl awich) Typical: <200 ns (approx. ±0.07* @ 1 kHz, ±2* @ 25.6 kHz)	changing from AC to DC coupling	or changing input range when DC	C coupled	<-9	0 dB	-10	0 dB
	Harmonic Distortion (all harmon	ics)		Guara	anteed	Тур	oical
Crosstalk: Between any two channels in different modules Frequency Range Guaranteed Typical Channel-to-Channel Match 0:0512.kHz -100 dB -140 dB Channel-to-Channel Match Maximum Gain Difference it, is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB fram lower frequency limit, fL (0.4 dB at -10%, filter frequency) Typical Maximum Phase Difference (within one frame) fL is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB fram lower frequency limit, fL (0.4 dB at -10%, filter frequency) 512.kHz ±0.05 dB Additional PTP sync. error (phase difference) between modules/trames (using a single standard gigabit switch) Typical: -200 ns (approx. ±0.07* @ 1 kHz, ±2* @ 25.6 kHz) Channel-to-Channel Match (316 V _{pask} input range) Maximum Gain Difference (within one frame) 0.6 dB from lower frequency limit, fL, to 51.2 kHz (1 db at -10%, filter frequency) Channel-to-Channel Match (316 V _{pask} input range) Maximum Gain Difference (within one frame) 0.6 dB from lower frequency limit, fL, to 51.2 kHz (1 db at -10%, filter frequency) Values for 31.6 V _{pask} input range Frequency Range Guaranteed Phase Match (only for using intensity Phase Match (only for using intensity Phase Match (only for using intensity filter and in 10 V _{pask} input range) Frequency Range Guaranteed Typical Phase Match (only for using intensity filter and in 10 V _{pask} input range) 10 to 120 Hz 250 Hz to 2.5 kHz 0.017* ±0.005*				–80 (–60 dB in 3	0 dB 81.6 V range)	–100 dB (–80 dB @ 1 kH;	@ 1 kHz z in 31.6 V range)
In different modules In different modules 0 to 51.2 kHz -100 dB -140 dB Channel-to-Channel Match (10 V _{peak} input range) Maximum Gain Difference to the high-pass filter 0.2 dB from lower frequency limit, f ₁ , 0.4 dB at -10% filter frequency a.0.05 dB Maximum Phase Difference (within one frame) f ₁ is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency a.0.05 dB Maximum Phase Difference (within one frame) f ₁ is defined as the -0.1 dB frequency of the high-pass filter Typical a.0.05 dB Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigabit switch) Typical: <200 ns (approx. ±0.07* @ 1 kHz, ±2* @ 2.5 6 kHz) Channel-to-Channel Match (316 V _{peak} input range) Maximum Gain Difference (within one frame) Guaranteed Typical: <200 ns (approx. ±0.07* @ 1 kHz, ±2* @ 2.5 6 kHz) Sound Intensity Phase Match (only for using intensity Phase Match (only for using intensity litter and in 10 V _{pak} input range) Frequency Range Guaranteed Typical Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 0.017* ±0.005* All channels matched 0 to 120 Hz 70 dB 80 dB Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 70 dB 80 dB Values	Crosstalk: Between any two char	nnels of a module or between any	two channels	Frequen	cy Range	Guaranteed	Typical
Channel-to-Channel Match (10 V _{peak} input range) Maximum Gain Difference t _L is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency (init, t _L to 15.2 kHz) ± 0.05 dB Maximum Phase Difference (within one frame) t _L is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency) ± 0.05 dB Maximum Phase Difference (within one frame) t _L is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency) ± 0.05 dB Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigabit switch) Typical: 200 ns (approx. ± 0.07" @ 1 kHz, ±2" @ 25.6 kHz) Channel-to-Channel Match (31.6 V _{peak} input range) Maximum Gain Difference (within one frame) 0.6 dB from lower frequency) Sound Intensity Phase Match (only for using intensity filter and in 10 V _{peak} input range) Frequency Range 250 Hz to 2.5 kHz Guaranteed Phase Match (10 Jar 2.50 G.4 kHz Typical Phase Match (10 Jar 2.50 G.4 kHz Common Mode Rejection in 10 V _{peak} input range 0 to 120 Hz 7 dB 8 ddB 10 VHz 0 do 12 Hz 7 dB 8 ddB 10 to 51.2 kHz 3 dd B 4 ddB 4 ddB Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 7 ddB 8 ddB 10 Hz Hz 3 dB </td <th>in different modules</th> <td></td> <td></td> <td>0 to 5</td> <td>1.2 kHz</td> <td>-100 dB</td> <td>-140 dB</td>	in different modules			0 to 5	1.2 kHz	-100 dB	-140 dB
(10 V _{peak} input range) Maximum Cain Difference IL is defined as the -0.1 dB frequency of the high-pass filter 0.2 dB from lower frequency (0.4 dB at -10% filter frequency) ±0.05 dB Maximum Phase Difference (within one frame) IL is defined as the -0.1 dB frequency of the high-pass filter Image: Comparison of the high-pass filter Image: Comparison of the high-pass filter Image: Comparison of the high-pass filter Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigati switch) Typical: <200 ns (approx. ±0.07* @ 1 kHz, ±2* @ 25.6 kHz)	Channel-to-Channel Match			Guara	anteed	Тур	pical
Maximum Phase Difference (within one frame) ft_ is defined as the -0.1 dB frequency of the high-pass filter Image: the transform of the high-pass filter is defined as the -0.1 dB frequency of the high-pass filter Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigabit switch) Typical: <200 ns (approx. ±0.07° @ 1 kHz, ±2° @ 25.6 kHz) Channel-to-Channel Match (31.6 Vpeak input range) Maximum Phase Difference (within one frame) 0.6 dB from lower frequency limit, ft_ to 51.2 kHz Sound Intensity Phase Match (only for using intensity filter and in 10 Vpeak input range) Maximum Phase Difference (within one frame) 0.6 dB from lower frequency limit, ft_ to 51.2 kHz Common Mode Rejection in 10 Vpeak input range Guaranteed Phase Match 10 Vpeak, input range Typical Phase Match 10 to 25.0 Hz ±0.017° Common Mode Rejection in 10 Vpeak, frames are 10 dB lower. 0 to 120 Hz 70 dB 80 dB 1 to 51.2 kHz 30 dB 40 dB Absolute Max. Common Mode Voltage 1 to 51.2 kHz 30 dB 40 dB Atleasing Filter Filter Type 3rd order Butterworth Atleast ange frequencies 0 dt order Indev to ange common mode value Atleasted 9 dB attenuation of those frequencies which can cause aliasing Filter Type 3rd order Butterworth Atleast 9 dB attenuation of those frequencies which can cause aliasing Filter Type	(10 V _{peak} input range)	Maximum Ga f _L is defined as the –0.1 of the h	ain Difference dB frequency igh-pass filter	0.2 dB from lower to 51 (0.4 dB at –10%	frequency limit, f _L , .2 kHz 5 filter frequency)	±0.0	05 dB
Additional PTP sync. error (phase difference) between modules/frames (using a single standard gigabit switch) Typical: <200 ns (approx. ±0.07° @ 1 kHz, ±2° @ 25.6 kHz)		Maximum Phase Difference (with f_L is defined as the –0.1 of the h	nin one frame) dB frequency nigh-pass filter	Max. phase diff.		6.4k	51.2k Hz 080229
Channel-to-Channel Match (31.6 V _{peak} input range) Maximum Gain Difference (within one frame) 0.6 dB from lower frequency limit, f _L , to 51.2 kHz (1 dB at - 10% filter frequency) Sound Intensity Phase Match (only for using intensity filter and in 10 V _{peak} input range) Frequency Range 250 Hz Guaranteed Phase Match 50 to 250 Hz Typical Phase Match (1 dD 10° All channels matched 50 to 250 Hz ±0.017° ±0.005° All channels matched 2.5 to 6.4 kHz ±0.17° ±0.08° Common Mode Rejection in 10 V _{peak} input range 0 to 120 Hz 70 dB 80 dB 120 Hz to 1 kHz 50 dB 60 dB 40 dB Absolute Max. Common Mode Voltage 0 to 120 Hz 70 dB 80 dB 1 to 51.2 kHz 30 dB 40 dB 40 dB Absolute Max. Common Mode Voltage ±5 V _{peak} without damage ±4 V _{peak} without damage #4 V _{peak} without clipping If common mode voltage exceeds the max. value, care must be taken to limit the signal ground current in order to prevent damage. Max. is 100 mA. The instrument will limit the voltage to the stated max. "without damage #1 east 90 dB attenuation of those frequencies which can cause aliasing Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which c	Additio	nal PTP sync. error (phase differe s/frames (using a single standard	ence) between gigabit switch)	Typical:	<200 ns (approx. ±0.0	07° @ 1 kHz, ±2° @ 3	25.6 kHz)
Maximum Phase Difference (within one frame) 4° from lower frequency limit, f _L , to 51.2 kHz Sound Intensity Phase Match (only for using intensity filter and in 10 V _{peak} input range) Frequency Range 50 to 250 Hz Guaranteed Phase Match ±0.017° Typical Phase Match ±0.005° All channels matched 250 Hz to 2.5 kHz 0.017° × (f/250) ±0.005° All channels matched 2.5 to 6.4 kHz ±0.17° ±0.08° Common Mode Rejection in 10 V _{peak} input range Guaranteed Typical Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 70 dB 80 dB 120 Hz to 1 kHz 55 dB 60 dB 40 dB Absolute Max. Common Mode Voltage ±5 V _{peak} without damage ±4 V _{peak} without dipping If common mode voltage exceeds the max. value, care must be taken to limit the signal ground current in order to prevent damage. Max. is 100 mA. The instrument will limit the voltage to the stated max. "without damage" common mode value Anti-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which can cause aliasing Filter Type 3rd order Butterworth -0.1 dB @ 51.2 kHz 51.2 kHz 51.2 kHz <th>Channel-to-Channel Match (31.6 V_{peak} input range)</th> <td>Maximum G</td> <td>ain Difference</td> <td colspan="2">0.6 dB from lower frequency limit, f_L, to 51.2 kHz (1 dB at –10% filter frequency)</td> <td>κHz</td>	Channel-to-Channel Match (31.6 V _{peak} input range)	Maximum G	ain Difference	0.6 dB from lower frequency limit, f _L , to 51.2 kHz (1 dB at –10% filter frequency)		κHz	
Sound Intensity Phase Match (only for using intensity filter and in 10 V _{peak} input range) Frequency Range Guaranteed Phase Match Typical Phase Match 10 V _{peak} input range) 50 to 250 Hz ±0.017° ±0.005° All channels matched 250 Hz to 2.5 kHz 0.017° × (t/250) ±0.005° All channels matched 2.5 to 6.4 kHz ±0.17° ±0.08° Common Mode Rejection in 10 V _{peak} input range Guaranteed Typical Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 70 dB 80 dB 120 Hz to 1 kHz 55 dB 60 dB 60 dB 1 to 51.2 kHz 30 dB 40 dB 40 dB Absolute Max. Common Mode Voltage ±5 V _{peak} without damage ±4 V _{peak} without damage Mati-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which can cause aliasing Filter Type 3rd order Butterworth -0.1 dB @ 51.2 kHz 51.2 kHz 51.2 kHz		Maximum Pha (with	ase Difference hin one frame)	4° from lower frequency limit, f _L , to 51.2 kHz			Z
	Sound Intensity Phase Match	Frequ	lency Range	Guaranteed	Phase Match	Typical Ph	ase Match
$ \begin{array}{ c c c c c c c c } \hline 250 \mbox{ Hz } 0.25 \mbox{ Hz } 0.017^{\circ} \times (f/250) & \pm 0.005^{\circ} \\ \hline \mbox{ All channels matched} & 2.5 \mbox{ to } 4.8 \mbox{ Hz } \pm 0.17^{\circ} & \pm 0.08^{\circ} \\ \hline \mbox{ Common Mode Rejection in 10 V_{peak} input range } & Guaranteed & Typical \\ \hline \mbox{ Values for 31.6 V}_{peak} range are 10 \mbox{ dB lower.} & 0 \mbox{ to } 120 \mbox{ Hz } 70 \mbox{ dB } & 80 \mbox{ dB } \\ \hline \mbox{ 120 Hz } to 1 \mbox{ Hz } & 55 \mbox{ dB } & 60 \mbox{ dB } \\ \hline \mbox{ 120 Hz } to 1 \mbox{ Hz } & 55 \mbox{ dB } & 60 \mbox{ dB } \\ \hline \mbox{ 120 Hz } to 1 \mbox{ Hz } & 30 \mbox{ dB } & 40 \mbox{ dB } \\ \hline \mbox{ Absolute Max. Common Mode Voltage } & & & & & & & & & & & & & & & & & & $	(only for using intensity filter ar 10 V _{peak} input range)	nd in	50 to 250 Hz	±0.	017°	±0.0	005°
Anti-aliasing Filter Attendiation of those frequencies which can cause aliasing Filter Type Slope -18 dB/octave		250	Hz to 2.5 kHz	0.017°	× (f/250)	±0.005°	
Common Mode Rejection in 10 V _{peak} input range Guaranteed Typical Values for 31.6 V _{peak} range are 10 dB lower. 0 to 120 Hz 70 dB 80 dB 120 Hz to 1 kHz 55 dB 60 dB 1 to 51.2 kHz 30 dB 40 dB Absolute Max. Common Mode Voltage ±5 V _{peak} without damage ±4 V _{peak} without clipping If common mode voltage exceeds the max. value, care must be taken to limit the signal ground current in order to prevent damage. Max. is 100 mA. The instrument will limit the voltage to the stated max. "without damage" common mode value Anti-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which can cause aliasing -0.1 dB @ 51.2 kHz -3 dB @ 128 kHz 51.2 kHz		2	2.5 to 6.4 kHz	±0	.17°	±0.08°	
Values for 31.6 Vpeak range are 10 dB lower. 0 to 120 Hz 70 dB 80 dB 120 Hz to 1 kHz 55 dB 60 dB 1 to 51.2 kHz 30 dB 40 dB Absolute Max. Common Mode Voltage ±5 Vpeak without damage ±4 Vpeak without clipping If common mode voltage exceeds the max. value, care must be taken to limit the signal ground current in order to prevent damage. Max. is 100 mA. The instrument will limit the voltage to the stated max. "without damage" common mode value Anti-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which can cause aliasing -0.1 dB @ 51.2 kHz -3 dB @ 128 kHz -18 dB/octave	Common Mode Rejection in 10	V _{peak} input range	0 to 100 LL-	Guara	anteed	Typical	
Image: International control in the second contexecond contexecond control in the second control in t	Values for 31.6 V _{peak} range are 10) dB lower.		70	dB	80	dB
Absolute Max. Common Mode Voltage ±0 0B 40 0B Absolute Max. Common Mode Voltage ±5 V _{peak} without damage ±4 V _{peak} without clipping If common mode voltage exceeds the max. value, care must be taken to limit the signal ground current in order to prevent damage. Max. is 100 mA. The instrument will limit the voltage to the stated max. "without damage" common mode value Anti-aliasing Filter Filter Type At least 90 dB attenuation of those frequencies which can cause aliasing -0.1 dB @ -3 dB @ 128 kHz Slope -18 dB/octave			1 to 51.2 kHz	30	dB	60	dB
Anti-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies which can cause aliasing Filter Type 3rd order Butterworth -0.1 dB @ 51.2 kHz -3 dB @ 128 kHz Slope -18 dB/octave	Absolute Max. Common Mode \	/oltage			+5 V with	nout damage	
Anti-aliasing Filter Filter Type 3rd order Butterworth At least 90 dB attenuation of those frequencies -0.1 dB @ 51.2 kHz which can cause aliasing -3 dB @ 128 kHz Slope -18 dB/octave				If common mode v signal ground curre will limit the voltage	±4 V _{peak} with oltage exceeds the ma ent in order to prevent e to the stated max. "w	hout clipping ax. value, care must t damage. Max. is 100 vithout damage" comm	be taken to limit the mA. The instrument non mode value
which can cause aliasing -0.1 dB @ 51.2 kHz -3 dB @ 128 kHz Slope -18 dB/octave	Anti-aliasing Filter At least 90 dB attenuation of those	frequencies	Filter Type		3rd order E	Butterworth	
−3 αB @ 128 kHz Slope −18 dB/octave	which can cause aliasing		-0.1 dB @		51.2	kHz	
			-3 aB @ Slope		128 18 dB	кнz /octave	

INPUT CHANNELS (CONTINUED)

Supply for Microphone Preamplifiers		± 14.0 V, max. 100 mA per channel (max. 100 mA total/module)	
Supply for Microphone Polarization		200 V ±1 V, or 0 V (Set per channel)	
Supply for CCLD (for example: Delta	ITron or ICP [®])	4 to 5 mA from 24 V source, option to DC-couple CCLD power supply	
Tacho Supply		CCLD for MM-0360 (Power supply for legacy Types MM-0012 and MM-0024 not available)	
Analog Special Functions	Analog Special Functions Microphone Charge Injection Calibration: All modules with 7-pin LEMO support CIC via dedicated software and OLE interface Transducers: Supports IEEE 1451.4-capable transducers with standardised TEDS (up to 100 m (328 f		
Overload Detection	 Signal Overload: Adjustable detection level ±1 V_{peak} to ±10 V_{peak}. Default level ±10 V_{peak} (CCLD mode ±7 V_{peak}) (31.6 V range: ±31.6 V) can be set in PULSE Transducer Database CCLD Overload: Detection of cable break or short-circuit + detection of CCLD transducer working point fault. Detection level: +2 V/20 V Microphone Preamplifier Overload: Detection of microphone preamplifier current consumption too high or too low. Detection level default 10 mA/1 mA Adjustable detection level 1 to 20 mA or 100 mA if disabled 		
Protection	If signal input level exceeds the measuring range significantly, the input will go into protection mode until the signal goes below the detection level again for at least 0.5 s. While in protection mode, the input is partly switched off and the input impedance is greatly increased. (The measured value will be strongly attenuated but still detectable) In DC mode –10 V _{peak} range, the detection limit is ±12 V. In all other measuring modes (except CCLD) the limit is ±50 V _{peak} including DC component or ±12 V _{peak} AC In CCLD mode the limit is +50/–2 V _{peak} including DC component or ±12 V _{peak} AC In the 31.6 V range, the limit is ±50 V _{peak}		

POWER REQUIREMENTS

DC Input: 10 to 32 V DC Connector: LEMO coax., FFA.00.113, ground on shield

Power Consumption:

DC Input: <15 W

Supply via PoE: According to IEEE 802.3af, Max. cable length 50 m

Temperature Protection:

Temperature sensor limits module's internal temperature to 80°C (176°F). If temperature exceeds limit, system will automatically enable fan in LAN-XI frame or shut down module outside frame

DIMENSIONS AND WEIGHT

Height: 132.6 mm (5.22") Width: 27.5 mm (1.08") Depth: 250 mm (9.84") Weight: 750 g (1.65 lb)

Ordering Information

Type 3056-A-040	4-ch. Input/HS-Tacho + 8-ch. Aux. Module LAN-XI
	51.2 kHz (Mic, CCLD, V)
includes the follow	ving accessories

• UA-2111-040: Detachable front panel with 4 BNC input connectors and 2 LEMO auxiliary connectors

OPTIONAL ACCESSORIES

UA-2110-040	Detachable front panel with 4 LEMO input connectors
	and 2 LEMO auxiliary connectors
AO-0090	7-pin LEMO to BNC male (1.2 m) for floating ground
AO-0091	7-pin LEMO to BNC female (1.2 m) for floating ground
AO-0526	4-pin Microtech to $3 \times BNC$ Cable
AO-0546	DC Power Cable, Car Utility Socket to 1 module
AO-0548	DC Power Cable, Source to 4 modules
AO-0738-D-010	Cable, for Type 3056, 2 × 10-pin LEMO (M) to 8 × BNC
	(F) 1.0 m (3.3 ft.), max. 70°C (158°F)
AO-1450	Shielded CAT 6 LAN Cable with RJ45 (2 m)
JJ-0081	BNC Adaptor, female to female
JJ-0152	BNC T-connector

JP-0145	BNC to 10–32 UNF Plug Adaptor
UL-0265	10-port Gigabit Managed Switch with PTP and
	PoE (8 ports)
WB-1497	20 dB Attenuator
ZH-0699	Break-out Box

SOFTWARE

Please refer to the System Data for PULSE Software (BU 0229)

SERVICE PRODUCTS

3056-CAI	Type 3056 Initial Accredited Calibration
3056-CAF	Type 3056 Accredited Calibration
3056-CTF	Type 3056 Traceable Calibration
3056-TCF	Type 3056 LAN-XI Conformance Test with Certificate

A wide range of Brüel & Kjær accelerometers, microphones, preamplifiers and sound intensity probes is available for use with a LAN-XI system. The system supports IEEE 1451.4-capable transducers with standardised TEDS. Please see www.bksv.com

TRADEMARKS

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Local representatives and service organisations worldwide

